Report # 2018-06

Processing and inversion of SkyTEM data leading to a hydrogeological interpretation of the Peace River North Western Area

Client: Geoscience BC

Peace River North-Western Area



In cooperation with



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Table of Contents

1. EXECUTIVE SUMMARY	3
2. INTRODUCTION	5
3. THE SKYTEM SYSTEM	6
4. DATA PROCESSING	7
5. INVERSIONS	11
6. COMPARISON WITH ANCILLARY DATA	13
7. HYDROGEOLOGICAL INTERPRETATION	15
8. COMMENTS ON RESULTS	25
9. MAPS	26
APPENDIX 1 (CROSS SECTIONS)	27
APPENDIX 2 (LIST OF DELIVERABLES)	37



1. Executive summary

This study is part of the Peace Project. The Peace Project is a collaborative effort involving Geoscience BC, the Ministry of Forests, Lands and Natural Resource Operations, the Ministry of Environment, the BC Oil and Gas Commission, the Ministry of Natural Gas Development, BC Oil and Gas Research and Innovation Society (BC OGRIS), Progress Energy Canada Ltd., and ConocoPhillips Canada, with additional support from the Peace River Regional District and the Canadian Association of Petroleum Producers. The authors of this report acknowledge the in-kind and funding support these partners have made to this study, through their contributions to the Peace Project.

This report covers the processing, inversion and (hydro)geological interpretation of the SkyTEM data over a portion of the entire SkyTEM survey acquired in the Peace Project. More specifically, it contains results covering the Peace River "North-Western" area.

The AEM and navigation data were first re-processed, starting from raw data, adopting state of the art methodologies aimed at reducing artefacts in the data, and therefore in the derived models. They were then inverted to 3D resistivity models using both Laterally and Spatially Constrained Inversions. Preliminary inversion results were analyzed against ancillary information and provided feedback for data post-processing and final inversions. An extensive set of high-resolution maps of electrical resistivity slices (1:50.000 scale) at different elevations and depths has been provided. The resulting 3D model was then correlated to known geological information to produce a hydrogeological model.

From a geophysical standpoint, the main results of this study include: spatial variability of the resistivity models reflecting potential changes in geology, both near surface and at depth; excellent fit between measured and modelled data, independent of geology or flight lines; seamless models, despite the data were acquired under varying conditions and over a period of several weeks; depth of investigation exceeding, in places, 300 m; effective removal of potential canopy effects; good correlation with depth to bedrock inferred from boreholes.

The derived qualitative geological interpretation highlights: differentiation of different facies within the glacial cover (e.g., resistive glaciofluvial deposits versus the more conductive glaciolacustrine deposits); confirmation of several near surface resistive features associated with paleovalleys and/or areas of thick Quaternary cover identified by previous studies of borehole data; presence of other near surface resistive features that could be of hydrogeological relevance; clear conductive response of the shale bedrock formations (Sully and Buckinghorse); predominantly resistive response of the sandstone Dunvegan bedrock formation; inconsistent response of the predominantly sandstone Sikanni bedrock formation (variability of the sandstone responses might be due to inhomogeneous grain size or water quality); presence of resistive units, in places, at the bottom of the Buckinghorse formation; presence of deep (in excess of 200 m) features with geological continuity, extending over significant distances.

The detailed hydrogeological interpretation and 3D modelling is mainly focused on buried palaeovalleys, which represent the most promising potential for sustainable groundwater production in the area. Some of those valleys were likely formed as tunnel valleys containing enclosed depressions that may be filled with coarse-grained material. At least two generations of valleys seem to be present separated by a widespread glaciolacustrine unit and fluvial sediments. These units, together with the older bedrock units, are included in a 3D model. Although only constructed for a small portion of the entire survey area, this model can potentially be used for planning future groundwater modelling.



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Geoscience BC is an independent, non-profit organization that generates earth science in collaboration with First Nations, local communities, government, academia and the resource sector. Our independent earth science enables informed resource management decisions and attracts investment and jobs. Geoscience BC gratefully acknowledges the financial support of the Province of British Columbia.



2. Introduction

This report is based on data delivered by SkyTEM Aps on behalf of Geoscience BC and processed and inverted by Aarhus Geophysics Aps. The following hydrogeological interpretation was led by GEUS (the Geological Survey of Denmark and Greenland). The data were collected using a SkyTEM 312 ^{Fast} airborne geophysical survey carried out in British Columbia (Canada) in 2015, covering a total of approximately 21,000 line km.

The new processed dataset consists of approximately 4500 line kilometres of AEM data, located in the North Western part of the Peace River Project (Figure 1).



Figure 1. The red polygon outlines the North-Western area. Adapted from Petrel Robertson, 2015.



3. The SkyTEM system

SkyTEM is a time-domain helicopter electromagnetic system designed for hydrogeophysical, environmental and mineral investigations. The system is shown in operation in Figure 2. The SkyTEM system is carried as an external sling load independent of the helicopter. The transmitter, mounted on a lightweight composite frame in an eight-sided polygon configuration, is a twelve-turn 337 m² eight-sided loop divided into segments for transmitting a low moment (LM) in two turns and a high moment (HM) in all 12 turns. The LM is about 5.9 A with a turn-off time of 18 μ s; the HM transmits in the range of 120 A and has a turn-off time ranging from 320 μ s. This yields a maximum magnetic moment of approximately 490.000 Am². The z-component receiver loop is placed approximately 2 m above the frame in what is practically a position of null primary magnetic field. Two lasers placed on the frame measure the distance to terrain continuously and two inclinometers measure the tilt of the frame. Power is supplied by a generator placed between the helicopter and the frame.



Figure 2. SkyTEM 312 Fast system.

Measurements are carried out continuously while flying. Every single transient is stored in a binary format, and pre-stacked. Measurements cover the time span from approximately 4.7 µs to 11.4 ms (centre times) from end of ramp. Refer to SkyTEM's report (Geoscience BC, 2016) for a detailed description of the gate times.

Altitude, TEM data and a number of instrument parameters are monitored and stored digitally so that they can be used for quality control during the data processing stage.



4. Data processing

The aim of advanced data processing is to prepare data for the inversion. This includes data import, data corrections, filtering and culling and discarding of distorted or noise-affected data. The remaining data are then averaged spatially using trapezoid filters of an optimal configuration, which allows increasing signal to noise level without compromising lateral resolution. Figure 3 shows the schematic block-diagram of the processing and inversion workflow. The processing is carried out using the SkyTEM module of the Aarhus Workbench software package.



Figure 3. Workflow for the data processing and inversion of SkyTEM data carried out with the Aarhus Workbench.

All data are marked with a time stamp, which links transmitter current, altitude, GPS coordinates, etc. During the processing a running mean is calculated separately for the X and Y direction tilt data while algorithms are used to automatically filter out bad altitude data - typically reflections from tree or bush tops.



In this survey, by virtue of the Primary Field Compensation (PFC) performed by SkyTEM, the first usable time gate in the low moment is around 2.5 μ s (gate 9) after the end of transmitter "ramp down".

The processing of voltage data is carried out in a two-step module, featuring automatic and manual modes. The navigation data is corrected for the transmitter/receiver tilt, and altimeter drops, while for the EM data other filters are employed which are designed to cull coupled or noise influenced data. Note: in order to preserve the integrity of the measured data, the processing is carried out on the raw data in binary format, rather than on the pre-filtered ASCII data.

In the next step, the automatically processed raw soundings are inspected visually using a number of different data plots. At this stage it is assessed whether the filters have removed the right amount of data coupled to man-made infrastructures. It is usually necessary to intervene manually to fine-tune the outcome of the filters and obtain the most reliable results. Figure 4 shows a view into the data processing module of the Aarhus workbench over a section of SkyTEM data from another survey, with data culled due to coupling with man-made structures.



Figure 4. The data processing window of the Aarhus Workbench, showing portions of data deleted because of coupling with man-made structures (top) and of random background noise (bottom).

Altimeter data are also assessed and edited, since an erroneous measure of ground clearance used as input to the inversion can produce artefacts in the resistivity models. The aim of altimeter filtering is to remove laser reflections, which are not coming from the ground, such as reflections from tree tops. This procedure is carried out with an algorithm, which is based on the fact that the reflections from the treetops result in lower apparent flight altitude, than the other reflections. The algorithm filters out the data by repeatedly making a polynomial fit to the data and then by removing data some meters below the latest polynomial fit. This automatic filtering is followed



by a manual inspection and in some cases manual refinements. This procedure is mostly needed in areas with very few ground reflections. In such areas, it can be advantageous to calculate another flight altitude based on the above sea level altitude from the GPS and a digital elevation model. While less accurate than the flight altitude based on the laser reflections from the ground, this flight altitude can be used to guide the manual refinements. Figure 5 shows an example of processing of laser altimeter data.



Figure 5. Example of processed laser altimeter data (brown line) versus raw measured data (green and red dots) in an area with canopy cover.

EM data are further averaged to increase the signal to noise ratio using a trapezoid shaped averaging core, where the averaging width of late time data is larger than that of early time data, as shown in Figure 6.



Figure 6. The principle behind the trapezoid shaped averaging core where data are averaged over larger time spans at later times to maintain as much lateral resolution as possible at early times while keeping a high penetration depth.

The data uncertainty for these stacked (averaged) soundings is calculated from the data stack. Furthermore, a minimum small uniform (or "floor") data uncertainty is assigned to all data. For the current study, this floor uncertainty has been set to 3%.



Soundings were produced for every 1.4 s corresponding to approximately 30 m distance from one another. The good signal levels recorded in large portions of the survey, allowed using trapezoid averaging filters of moderate width. Table 1 provides a summary of the automatic filters applied to the dataset.

	LM	НМ
Distance between averaged soundings (s)	1.4	1.4
Time of first trapezoid knee point (T1)	1e-5	1e-4
Time of second trapezoid knee point (T2)	1e-4	1e-3
Time of third trapezoid knee point (T3)	1e-3	1e-2
Width of first trapezoid section (width 1)	3	3
Width of second trapezoid section (width 2)	5	5
Width of third trapezoid section (width 3)	8	10

Table 1. The settings for the automated filters employed in the first part (automatic filtering) of the processing, for the low (LM) and high (HM) moment of the SkyTEM system. All the above times are expressed in seconds.

After the automatic stacking, soundings are inspected visually using a number of different data plots. At this stage it is assessed whether data points at late times should be ascribed a higher uncertainty or removed entirely. It is customary to cull data when the background noise level reaches the level of the earth response. Assessing data for usability is done by inspecting the decay curves, the distance to potential noise sources and the level of the background noise.

This process is necessary to gain reliable model parameters in all parts of the data sections. Figure 7 shows one averaged sounding (transformed into a version of late time apparent resistivity), with different time gates displaying different noise levels, for low and high moment. These curves (not normalized with Tx current) are used only for data editing.



Figure 7. Example of averaged sounding (transformed into late time apparent resistivity), with different time gates displaying different noise levels, for low and high moment.



5. Inversions

Preliminary inversions are carried out using the quasi 2-D Laterally Constrained Inversion (LCI). Final inversions are carried out using the quasi 3-D Spatially Constrained Inversion (SCI). LCI and SCI are full non-linear damped least squares solutions in which the transfer function of the instrumentation is modelled. This includes, among other things, current turn-on and -off ramps, front gate and low pass filters, system altitude, etc. The inversion kernel is "AarhusInv", designed by the University of Aarhus. This code performs efficient large-scale inversions and is crucial for testing inversions as well as examining the model space. Figure 8 shows a sample from the geometry file, describing the SkyTEM system used in this project.

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Figure 8. Sample of geometry file used to describe the SkyTEM system when modelling FWD responses.

Preliminary LCIs served the purpose of fine tuning the post-processing of the EM data, in terms of both couplings and noise assessment.

In the SCI scheme the model parameters are tied together spatially with a spatially dependent covariance, which is scaled according to the distance between neighbouring stations. Constraining the parameters tends to enhance the resolution of resistivities and layer interfaces, which are not well resolved in an independent inversion of the soundings. The flight altitude is included as an inversion parameter with a prior value calculated from the tilt corrected laser altitudes. The standard deviation on this parameter is set to 1 m.

The SCI inversion scheme is developed using 30 layers (each layer having a fixed thickness and varying resistivity). Regularization (incorporating our a-priori knowledge or assumptions) consists



of a vertical smoothing constraint term (smooth inversion) applied to stabilize the inversion, e.g. to remove fictitious layers especially in models based on few data points. The lateral constraints, which get tighter for deeper layers, were set on absolute elevation (rather than on depth), due to the geological settings of the area, which suggests greater degree of continuity of electrical resistivity within the same absolute elevation intervals.

The depth of investigation (DOI), based on an analysis of the Jacobian matrix, was also calculated for the output models. This DOI, is presented in a dedicated horizontal map, as well as superimposed to crop the average resistivity horizontal maps, and as a fading of colours below the DOI on the vertical cross sections. The DOI represents the maximum depth below surface to which there is little or no sensitivity to the model parameters. Any model parameter resting much below the DOI should be disregarded. For example, the DOI often rests at, or close to, an interface between a conductive overburden and a resistive deeper layer. In this case we can conclude that the conductive layer does end at that interface, and it rests above a significantly more resistive layer, whose absolute resistive value is poorly determined.

The multi-layered model uses fixed thicknesses discretized into 30 layers; however the resistivity value of each layer remains a free parameter to be fit during the inversions. It was discretized to 400 m, with layers logarithmically increasing in thickness, with the upper most (shallow) layer starting at 3 m. Dozens of preliminary inversions were carried out, carefully fine tuning the settings of regularization, convergence, DOI, uncertainties. Table 2 below summarizes the main settings (homogeneous at all depths) of the final SCI. The vertical constraints are purposely left loose, in order to allow sharp vertical variations in the resistivity models.

A higher halfspace resistivity was used for the starting model of the North Western corner of the area, where the bedrock is mainly formed by limestones and dolomites.

Resistivity starting model (ohm-m)	40 in general (100 for the NW corner)
Vertical Constraints	3 (with exception of first layer, =2)
Lateral Constraints	1.3
Reference distance (m)	40
Power law distance drop off	0.5

Table 2. SCI settings.

A number of boreholes provided by the client describing depth and type of bedrock were inspected and used for comparison with inversion results (cfr Section 6). However they were deemed not suitable to be used as extra input to the inversions, as a-priori, due to both their localized nature and the lack of downhole resistivity measurements. It is expected that if and when data describing physical properties of the subsurface becomes available (e.g., shallow seismic), they could be incorporated to refine the local inversions, and ultimately the interpretation.

The inversion results are presented as a series of both horizontal and vertical slices. The maps of average resistivity at different horizontal intervals are given in elevation above mean sea level. All models are masked by DOI and shown with corresponding data fit.



6. Comparison with ancillary data

The inversion results obtained in this study were compared against three different types of ancillary data. In section (6.1) a number of boreholes describing depth and type of bedrock were inspected and used for comparison with resistivity cross-sections. The inversion results were then assessed in plan view (6.2) against maps of paleo valleys and isopachs of Quaternary sediments (Hayes et al., 2015).

The following simplified hydrogeological settings are considered. The Quaternary sediments comprise the unconsolidated cap, typically no more that 15m in thickness. This overburden is of varying origin; namely, glacio-fluvial deposits (sands, pebbles and gravels), glacio-lacustrine deposits (silty clays or clayey silts), and tills. Moreover, there can be admixtures of colluvial (sandy and clayey silts) and fluvial units (mainly sands and gravels) generally limited to the existing river valleys, but sometimes related to pre-existing river channels. The underlying bedrock is comprised of Cretaceous-aged shale and sandstone formations, namely, the Dunvegan (sandstones and conglomerates), Sully (shales and siltstones), Sikanni (sandstones) and Buckinghorse (shales). Two geological formations were added, which had not been encountered in the previous projects: Lower Buckinghorse (most likely shales) and Nordegg (calcareous mudstones). The former seems to display a higher resistivity than the Buckinghorse (see Section in Figure A3) but we do not have enough data to confirm this behaviour. On the contrary, Nordegg has a clear resistive response, even though influenced by degree of fracturing and other possible local variations.

6.1. Comparison of cross-sections of inversion results against boreholes

Several vertical cross sections are provided in Appendix 1. Figures A2 to A6 display a selection of vertical resistivity sections overlain by simple borehole information, i.e., thickness of Quaternary sediments, depth to and type of bedrock. Profiles locations are shown in Figure A1.

These sections

a) do not coincide with individual flight lines, but rather connect boreholes

b) do not interpolate the resistivity models, but rather the actual resistivity models are projected onto the profiles from a maximum distance of 200 m.

The borehole data, on the other hand, are projected from a maximum distance of 500 m.

From a purely geophysical standpoint, the inverted resistivity models display satisfactory misfit, and significant Depth of Investigation, ranging in the order of 200 m to 300 m.

The models recover depth to bedrock with good accuracy, both shallow, within the majority of the area, and in the few instances where paleovalleys cut deeper into it. Some formations (e.g., Sully) show consistent resistivity responses, while others (e.g., Sikanni and Dunvegan) vary. This can be due either to water quality variations, local inhomogeneities (facies variations) in the rock matrix or both. The Quaternary units also display a degree of lateral variations in resistivity, probably due to the presence of glaciolacustrine deposits.

As will be examined in detail in the next section, some resistive structures within the Quaternary coverage were considered potential buried valleys filled with gravels and sands; they could have interest from a hydrogeological point of view, as they could represent exploitable aquifers.

The qualitative interpretation of the resistivity sections in Figures A2 to A5 is based on the integration of borehole data and previously known stratigraphic information (the formations accompanied by question marks). These qualitative interpretations provided the building blocks for further integrated studies and more advanced hydrogeological modelling.

Provided that a more detailed discussion about the Quaternary setting, especially about buried valleys and glacial deposit features, will be treated on the next chapter, the cross-sections confirm complicated pattern of bedrock formations: we can recognize huge plicative deformations, with



the definition of anticlines and synclines. The general response of the main formations is well confirmed: mainly resistive for Dunvegan and Sikanni, clearly conductive for Sully and Buckinghorse. Even though outside the scope of this project, we note that the Lower Buckinghorse unit seems to display a more resistive response, and might represent a potential hydrocarbon exploration target worth following up.

Several more buried valleys are recognizable beside the ones treated in the geological modelling. They display a complex geometry with very thick resistive buried valleys (reaching depths of 100 m and more), sometimes separated by conductive glacio-lacustrine lenses. The main structures are located along the Halfway River.

6.2. Comparison of horizontal sections of inversion results against known geology

Maps 1.RHO.005, 1.RHO.010, 1.RHO.015 and 1.RHO.020 (see Appendix 2 for details) display slices of near surface resistivity, obtained from SCI, plotted over surface geology. The resistivity models show a large degree of spatial variability. Exposed bedrock in the eastern portion of the area correlates well with conductive features. Some resistive features are in reasonable agreement with outlines of paleo-valleys and thick Quaternary aquifers inferred from the borehole data (reinterpreted gamma logs), while other features do not correlate.

A discussion about some selected resistivity maps is reported in Appendix 1.

Resistivity maps at intermediate depths display many other features worthy of consideration. Refer to the files containing a complete overview of resistivity slices at different elevations and depth intervals.



7. Hydrogeological interpretation

7.1 General interpretation of bedrock

A preliminary geological interpretation has been undertaken for the entire dataset in the North Western area. The geological interpretation of this area is consistent with the interpretation of the area to the Southeast (Jørgensen et al. 2016). The northwesternmost part of the area, around Pink Mountain, older formations are present. These comprise the Monteith and the Gething Formations as well as very resistive limestones of the Triassic. Also the Nordegg formation is included into this stratigraphic succession. These formations are heavily deformed in this region and also excavated where the Halfway River crosses Pink Mountain (Hinds & Cecile et al. 2003).

Apart from the Pink Mountain area, the lithostratigraphic formations within the penetration depths of the SkyTEM method are from below: (i) the Buckinghorse Formation (shales, silty mudstones and siltstones), overlain by, (ii) the Sikanni Formation (alternating layers of sandstone, siltstone and shale), (iii) the Sully Formation (mainly shales and siltstones) and finally topped by (iv) the Dunvegan Formation (sandstones and conglomerates). According to electrical logs the Sikanni Formation has a resistivity value between 15-20 ohm-m, the Sully Formation between 10-15 ohm-m, and the Dunvegan Formation shows resistivities between 15 and 50 ohm-m. The Dunvegan Formation constitutes the uppermost bedrock in the study area.

The geological interpretation is shown on two representative cross sections. The location of the cross sections is shown in Figure 9. Estimated thrust faults are delineated with thick red dotted lines and inferred bedrock formation boundaries are delineated by thick grey lines. Interpretations in the drift succession are delineated by thin black dotted lines. The cross sections are shown in Figure 10.





Figure 9: Elevation map of study area with location of cross sections (pink lines), 3D model area (blue polygon), mapped buried palaeovalleys (black lines).





Figure 10: Cross sections with geological interpretations. Estimated thrust faults are delineated with thick red dotted lines and inferred bedrock formation boundaries are delineated by thick grey lines. Interpretations in the drift succession are delineated by thin black dotted lines. The DOI is shown with a thin grey dotted line. Location of cross sections is shown in Figure 9. Vertical exaggeration 10x.

In the deeper part of the cross sections to the NE and at shallow to medium depths towards the SW, a thick unit of medium to low resistivity is recognized. This unit is interpreted as a clay-rich succession corresponding to the Buckinghorse Formation. The interpretation of the lower boundary of this unit is very uncertain, since it seems to be situated below or approximately at the same level as the DOI. In the northeastern part of the sections the upper boundary is also hard to estimate. Here it is due to large depths and the presence of the conductive Sully Formation above. Since the Buckinghorse Formation is difficult to penetrate, the thickness of the formation is difficult to estimate. What is below the Buckinghorse has therefore not been interpreted.

Above the Buckinghorse, an up to 200 m thick, more resistive unit is recognized. This is interpreted as the Sikanni Formation where the sandy parts make the unit more resistive compared to the Buckinghorse Formation. These two units are clearly thrusted and folded with the thrust faults dipping towards the NE. On top of the Sikanni Formation, an up to 150 m thick, conductive unit follows. This unit corresponds to the clay-rich lagunal deposit of the Sully Formation. The generally resistive layers present at high elevations on the mountain tops, and above the Sully Formation is interpreted as the Dunvegan Formation. The heterogeneous resistivity pattern in this formation reflects the interbedding with conglomerates, shale and coal.

The main structural features dominating the cross sections are an anticline/thrust at 22,000 m in Profile A and at 14,000 m in Profile B. Towards the Southwest this is followed by synclines. One large syncline in Profile A (app. 13,000 – 20,000 m) contains a huge body of the Sikanni sandstone. The next syncline is seen on both profiles and this is where the Halfway River flows (app. 5,000 – 12,000 m on Profile A). A considerable succession of drift sediments is found along this valley and its western tributaries.

The geological interpretations of the bedrock are outlined on a selected horizontal resistivity slice (see Figure 11, and Appendix 1).





Figure 11: Horizontal resistivity slice at 765 m above sea level. The major geological formations are outlined.

7.2 Buried valleys/palaeovalleys

Special attention has been placed on buried valleys, especially within and in the vicinity of the Halfway River valley where their occurrence seems to be more frequent than in the rest of the study area. A number of buried valleys have been mapped, see Figure 9. They are seen in the resistivity data as elongate resistive structures that broadens upwards through the resistivity model.

These buried valleys occur in at least two generations. The first generation is situated below an extensive unit of glaciofluvial sediments and glaciolacustrine clay found in large parts of the Halfway River valley and its tributaries. The second generation seems to be younger, cutting down into the glaciofluvial and glaciolacustrine units and into the first generation of buried valleys (see Figure 10).

The first generation of buried valleys have overdeepened sections along their thalwegs and may therefore be interpreted as subglacially formed tunnel valleys that are now buried by younger sediments. Tunnel valleys are cut into the subsurface at the glacier bed by pressurized meltwater. Such type of buried valleys are frequently found within all formerly glaciated areas (e.g. Jørgensen and Sandersen 2006). In geometry the valleys resemble the ones mapped with AEM in other parts of the world, we thus interpret the valleys as tunnel valleys.



The formation of the second generation of buried valleys is connected to recent, and eventual pro-glacial, fluvial erosion. Those buried valleys are limited in depth and are found beneath many stretches of modern rivers, such as the Halfway River and its tributaries.

The extensive unit of glaciofluvial sediments and glaciolacustrine clay found between the two generations of valleys is well known from outcrops and geological maps (Petrel Robertson 2015). Especially the upper part, which is a clay rich glaciolacustrine clay, is well resolved in the SkyTEM data. In the SkyTEM data it is seen as a thin conductive layer. The outwash sediments below have high resistivities.

Two long tunnel valleys seem to occupy the lower part of the drift succession along the Halfway River valley. One of these can be followed from the southernmost part of the area until where the Chowade River branches, see Figure 9. Here it bends towards the West and follows the Chowade River valley. A cross section along the thalweg of the valley is shown in Figure 12. The tunnel valley seems to be more than 100 m deep at its deepest depressions. Since the valley fill becomes more conductive with depth it appears to be getting more fine-grained in the deeper parts. The outwash unit on top, however, is very resistive indicating coarse-grained sediments.



Figure 12: Cross section from north (left) to south (right) along the thalweg of the long tunnel valley following the southern part of the Halfway River valley in the study area. The grey lines indicate interpretations of the valley and the layers above. Note the undulating bottom profile. The valley fill seems to be more conductive with depth indicating more clayey sediments in the deeper part.

The second long tunnel valley is found beneath the northernmost stretches of the Halfway River valley (Figure 9). It can be followed until it crosses Pink Mountain in the far North. This valley is up to about 75 m deep in its northern part (see Figure 13). These valleys have subsequently been cut by modern river streams along large sections of their length and in these sections it is difficult to distinguish between the modern river sediments and the older tunnel valley fill. The uncertainty of the interpretations is thus relatively high here.



Figure 13: Cross section from north (left) to south (right) along the thalweg of the long tunnel valley following the northern part of the Halfway River valley in the study area. The grey lines indicate interpretations of the valley and the layers above. Note the undulating bottom profile.

7.3 Detailed geological 3D model



The 3D geological model was constructed using the geological software modelling tool 'Geoscene3D' from I-GIS. The model area is situated in the southwest (Fig. 9) and covers an area corresponding to approximately 19 km E-W x 8 km N-S. The model area covers a section of the long tunnel valley that follows the southern part of the Halfway River valley (profile distance 10000m to 18000m in Fig. 12). In the following, this valley is named 'buried valley 1'. Figure 14 shows a close-up of the surface geology map in the model area together with the outline of the interpreted buried valleys and the position of the profiles in Figures 16 and 17.



Fig. 14: The model area (grey) shown on top of the surface geology map by Petrel Robertson, 2015. Outline of the interpreted buried valleys are shown with blue. Location of the profiles in Figs. 16 and 17 are shown (named 'flightline N1' and 'flightline N13').

The geological modelling is performed using a combination of layer- and voxel modelling. The bottom of each geological unit is modelled using interpretation points that have been kriged into surface layers. The bottom of four overall stratigraphic boundaries have been modelled; Buckinghorse Fm, Sikanni Fm, Sully Fm and Dunvegan Fm. In the valley, the bottom of 6 Quaternary boundaries have been modelled; Buried valley 1, buried valley 2, buried valley 3 (Fig. 14), the meltwater plain, the modern valley fill and the glaciolacustrine deposits.

Subsequently, a voxel model is constructed by using the tools described in Jørgensen et al. (2013). The final voxel model is discretized with 100 m x 100 m laterally and 5 m vertically and covers the elevation interval from 300 m.a.s.l. (meters above sea level) to the terrain surface (up to 1210 m.a.s.l.), resulting in c. 7.7 million voxels. The voxel model is constructed by selecting and populating voxels within volumes delineated by the modelled layer surfaces and defined regions. Overall, the units correspond to the ones defined by the layer surfaces, but two of the units ('Buried valley 1' and the 'Dunvegan Fm') are subdivided into lithological facies based on the resistivity values within the units (Table 3). The other Quaternary units are modelled as homogeneous units. The stratigraphic formations are known to be heterogeneous, but due to the greater burial depth of these formations, the SkyTEM data are not able to resolve the small lithological variations and resistivity values are therefore not used for lithological characterization within these units. Consequently, the voxel model consists of 13 categories, which are shown in Figure 15.

Table 3: Subdivision of geological units in the voxel model based on resistivity values within the units.



	Resistivity below 60 ohm-m	Resistivity above 60 ohm-m
Buried valley 1	Clayey valley fill	Sandy and gravelly valley fill
Dunvegan Fm	Silty shale	Sandstone and/or pebble conglomerate



Fig. 15a,b: 3D view of the model results seen from southeast. 5 x vertical exaggeration, a) 3D view of the voxels, b) E-W and N-S slices through the model shown together with the layer surface outlining buried valley 1.

Figure 15 shows 3D views of the model results. East of the valley, a synclinal structure is recognized in the northern part of the model area (Fig. 16), whereas a thrust fault structure is recognized below the Buckinghorse Fm in the southern part (Fig. 17). The Sully and Dunvegan Formations are only present in the southeastern part of the model (Fig. 15).

Quaternary deposits have only been modelled within the modern valley structure (Fig. 15), since the remaining part of the area generally shows a thin cover of Quaternary sediments (Fig. 14) with thicknesses below the vertical discretization in the voxel grid (<5m). In the modern valley structure, the Quaternary deposits have thicknesses between 20m to approximately 250m, where the buried valleys are deepest.

Three buried valleys are modelled within the model area. The largest is the one named 'buried valley 1'. This corresponds to the southernmost long tunnel valley described in Section 6.2 (Fig. 12), and it is located directly below the modern river in the southern part of the model (Fig. 17, profile distance 9000m). In the north, it is located below an erosional remnant of glaciolacustrine deposits (Fig. 16, profile distance 7700m). The lower part of the valley is mainly filled with clayey deposits, whereas the upper part has coarse-grained infill. Close to the hill-side in the eastern side of the modern valley, buried valley 2 is located and filled with mainly coarse-grained deposits.



Buried valley 3 is located in the northwestern part of the model area (Fig. 14) and is filled with clayey deposits.

All three buried valleys are interpreted to be first generation tunnel valleys that are older than the meltwater plain. The coarse-grained deposits from this unit therefore cut through the buried valley structures (Figs.15, 16 and 17). Glaciolacustrine clays are modelled on top of the meltwater plain, and in the north, a marked erosional remnant of these glaciolacustrine deposits forms a small hill structure in the middle of the modern valley (Fig. 15, and 16, profile distance 7200-8200m). The youngest deposits in the geological model is the sand and gravel deposits from the modern river bed, which is cut into the underlying deposits (e.g. Fig. 16, profile distance 8800-9800m).



Buried valley 1 (sand fill) Buried valley 3 (clay fill) Modern valley fill (sand and gravel) Fig. 16 a,b: a) SkyTEM resistivities and the DOI along the northernmost flightline within the 3D model area (flightline N1 in Fig. 14), b) geological model results along the same profile. 5x vertical exaggeration.





Fig. 17 a,b: a) SkyTEM resistivities and the DOI along the southernmost flightline within the 3D model area (flightline N13 in Fig. 14), b) geological model results along the same profile. Note that the Dunvegan Fm is subdivided into a clayey and non-clayey fraction. 5x vertical exaggeration.

7.4 Hydrogeological perspectives

Although hydrological data are not available from the area, the interpretation of the new SkyTEM data indicates that the buried valley structures and the covering outwash sediments could represent groundwater reservoir potential. The buried valleys are eroded into the Buckinghorse Formation that mainly consists of shale and mudstone with a low hydraulic conductivity and no groundwater potential.

The infill sediments in the buried valleys show varying resistivities, so the potential most likely also varies within each structure. Even though the meltwater plain and the buried valley 2 are modelled as coarse-grained units, both of these units show varying resistivities from around 40 to 100 ohm-m. Deposits with resistivities below 60 ohm-m are expected to show an increased clay content. The highest resistivities are found within the modern river bed (>100ohm-m), thus indicating coarse-grained sediments without much clay. In many places, the modern river bed is in direct contact with deposits in the meltwater plain and/or the buried valley structures (e.g. Fig. 17, profile distance 8,000 - 9,500m). Due to the direct hydraulic contact between the modern river bed and the possible aquifers beneath, groundwater extraction here could cause a depletion in river flow due to strong groundwater-surface water interaction. The groundwater extraction potential is in many places therefore dependent on the existence of a hydraulic barrier between the aquifers and the river bed. The most interesting sites for groundwater extraction could therefore be within the sand-filled parts of the buried valley structures, or in the meltwater plain, where those units are not in a direct hydraulic contact with the modern river bed.

Outside the 3D model area potential sites for groundwater extraction could be at local deepenings along the buried tunnel valleys, e.g. at distance 11,000 m in the northernmost long tunnel valley (see Figure 13). At this particular site, the tunnel valley is covered by the glaciolacustrine clay and therefore not in close contact with the river. The resistivity of the valley fill decreases when it is covered by conductive glaciolacustrine clay (Figure 13), but this is inferred to be an artifact



resulting from the inversion: the resistive fill cannot be fully resolved here due to the limited thickness of the layer.



8. General comments on the EM data processing and inversion results.

The results of the processing and inversion project are overall satisfactory, suggesting a positive outcome of the used techniques.

The processing of the navigation data required careful manual inspection and editing large areas covered by canopy.

The models produced are, to the best of our knowledge, void from significant cultural artefacts. It must however be stated that the lack of information about buried infrastructures added a degree of complexity and uncertainty to the processing of the EM data.

The settings for the final inversions were based on the analysis of several different preliminary realizations, assessed against the relevant ancillary information available. The regularization was chosen to best fit the geological settings of the area, with sharp vertical boundaries and spatial constraints limiting the variance with respect to absolute elevation.

The data misfit (normalized by standard deviation) is generally low (around 1) and homogenous throughout the entire data set, which is indicative of proper discretization, regularization and processing. The Depth of investigation ranges between 200m and 300m. No suitable ancillary data (e.g., pre-existing geological model, or large scale complementary geophysical data) were available to constrain the inversions over large areas. It is anticipated that, e.g., surfaces derived from seismic data, could be incorporated into future inversions to produce refined results.

The results are presented as an entire suite of resistivity maps at different absolute elevation intervals to be more representative of the geological settings. A limited number of near-surface resistivity maps at four depth intervals are also provided, to allow immediate correlation with the maps of depth to bedrock. The resistivity models reflect the significant spatial hydrogeological variability of the area. They are in good agreement with the available ancillary information and prior hydrogeological knowledge, both near surface and at intermediate depth. The models provide new insight into complex local near surface alluvial features as well as into large-scale structures. They also image large structures of geological appearance within bedrock, at depths where no ancillary information is currently available. Overall, the results present a valid base for further data integration and hydrogeological interpretation.



9. Thematic maps and sections

To visualize the processing and inversion results in the survey area, a number of theme maps and vertical sections were prepared. The colour scale for both average resistivity maps and vertical cross sections is a rainbow colour scale with hot colours representing resistive domain and cold colours representing conductive domain. A complete list of all final deliverables is provided in Appendix 2.

All final maps, except when stated otherwise in the legend, have been made using the kriging method (no nugget, exponential fitting), with a search radius of 1000 m and 30 m node spacing. We now present a brief explanation of the key maps mentioned above, and their use.



Selected references

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Appendix 1

This Appendix contains a few vertical resistivity cross sections and resistivity slice maps, mentioned in Section 6.1.

Figures A2 to A5 display a selection of vertical resistivity sections (W-E) overlaid with simple borehole information, i.e., thickness of Quaternary sediments, depth to and type of bedrock. The location of the profiles are provided in Figure A1. Notice that these section a) do not coincide to individual flight lines, but rather connect boreholes, b) do not show any interpolation of the resistivity models, but rather use the actual resistivity models that are projected onto the profiles from a maximum distance of 200 m. The borehole data, on the other hand, is projected from a maximum distance of 300 m.



Figure A1. Location of cross-sections shown in Figures A2 to A9, overlaying map of surficial geology, buried valleys and thicker sediments inferred from borehole data (adapted from Petrel Robertson, 2015). Boreholes are represented by the black dots.





Figure A2. Vertical resistivity cross sections P1 (top) and P2 (cfr Figure A1 for location) compared to borehole data (depth to and – color coded- type of bedrock), overlain with preliminary qualitative interpretation of main structures. Distance (m) from drillhole location shown above the boreholes. Models are shaded with DOI and show associated data misfit (black line, to be read against right axis).





Figure A3. Vertical resistivity cross sections P3 (top) and P4 (cfr Figure A1 for location) compared to borehole data (depth to and – color coded- type of bedrock), overlain with preliminary qualitative interpretation of main structures. Distance (m) from drillhole location shown above the boreholes. Models are shaded with DOI and show associated data misfit (black line, to be read against right axis).





Figure A4. Vertical resistivity cross sections P5 (top) and P6 (cfr Figure A1 for location) compared to borehole data (depth to and – color coded- type of bedrock), overlain with preliminary qualitative interpretation of main structures. Distance (m) from drillhole location shown above the boreholes. Models are shaded with DOI and show associated data misfit (black line, to be read against right axis).





Figure A5. Vertical resistivity cross sections P7 (top) and P8 (cfr Figure A1 for location) compared to borehole data (depth to and – color coded- type of bedrock), overlain with preliminary qualitative interpretation of main structures. Distance (m) from drillhole location shown above the boreholes. Models are shaded with DOI and show associated data misfit (black line, to be read against right axis).



Figures A6 to A10 display a selection of resistivity slice maps. The first one shows the correlation between outcropping geology and shallow resistivity (0-5 m depth), confirming the electrical response of the geological formation. Notice the good resolution of the elongated resistive Quaternary deposit associated to the Halfway River and its tributary Chowade River: they can be associated to buried valleys detected in Section 7. Of course, the resistivity distribution is strongly influenced by topography, hence it is hard to follow geological structures. For this purpose it is better to make use of maps in elevation (m a.s.l.).



Figure A6. Resistivity slice map at depth of 0-5 m.



Figure A7 is referred to 890-900 m a.s.l. and it is able to distinguish a very interesting resistive feature (a buried valley) within the Quaternary coverage on the Northern and in the Central area. As already evidenced in the previous project, there is a clear N-S pattern of the bedrock formations, with older and older rocks going Westward. The occurrence of anticlines causes sometimes the interposition of deeper formations between younger ones (e.g. the resistive feature of Sikanni within Sully on the Southern side).



Figure A7. Resistivity slice map at elevation 890-900 m a.s.l.

Going deeper (Figure A8, 840-850 m a.s.l.) we can see a progressive shift of the contacts within the bedrock Eastward, due to the general Westward dipping. However, the occurrence of anticlines can interrupt this



trend. The width of the buried valleys decreases in the Northern area, while new ones begin to appear to the South, where the elevations are lower.



Figure A8. Resistivity slice map at elevation 840-850 m a.s.l.

At 790-800 m a.s.l. the resistive feature of the Chowade River becomes sharp, together with other buried valleys along the Halfway River (to the East and to the South). At this elevation the Dunvegan formation is almost disappeared. The axis of an anticline, causing the uplift of Sikanni, is well imaged on the Southern side.





Figure A9. Resistivity slice map at elevation 790-800 m a.s.l.

The 740-750 m a.s.l. resistivity slice map (Figure 10) images very well the resistive Quaternary deposit along the Chowade-Halfway River system. A smaller resistive feature appears along the Cameron River, to the East.





Figure A10. Resistivity slice map at elevation 740-750 m a.s.l.





Figure A11. Horizontal resistivity showing the resistivity at 700 m, 725, 750 m and 775 m above sea level. Mapped buried valleys are outlined on the maps. They are mainly sees as elongate resistive structures. Only segments of the individual valleys are present at each slice because the valleys does not occupy the same levels along their entire stretches – in general they increase in level towards Northeast or they ondulate along their thalwegs with local deepenings.





Figure A12. Horizontal resistivity showing the resistivity at 800 m, 825 m, 850 and 875 m above sea level. Mapped buried valleys are outlined on the maps. They are mainly sees as elongate resistive structures. Only segments of the individual valleys are present at each slice because the valleys does not occupy the same levels along their entire stretches – in general they increase in level towards Northeast or they ondulate along their thalwegs with local deepenings.





Figure A13. Horizontal resistivity showing the resistivity at 900 and 925 m above sea level. Mapped buried valleys are outlined on the maps. They are mainly sees as elongate resistive structures. Only segments of the individual valleys are present at each slice because the valleys does not occupy the same levels along their entire stretches – in general they increase in level towards Northeast or they ondulate along their thalwegs with local deepenings.



Appendix 2

The following deliverables are provided to Geoscience BC for this phase of the Peace River Project:

- 1. Final inversion database (in Oasis Geosoft GDB format)
- 2. Final maps (in Oasis Geosoft Montaj MAP and PDF formats)
- 3. Current report (in PDF format)

Final inversion database

Channel	Unit	Description	
Х	m	X – coordinate (projected in WGS 84, UTM zone 10N)	
Y	m	Y – coordinate (projected in WGS 84, UTM zone 10N)	
Z	m	Z-coordinate in units of absolute elevation (array of 29 channels)	
Longitude	dega	Geographic longitude coordinate (WGS 84) in "normal" (decimal degrees) format	
Latitude	dega	Geographic latitude coordinate (WGS 84) in "normal" (decimal degrees) format	
FID	N/A	Fiducial	
LINE	N/A	Flight line number	
RECORD	N/A	Record number generated by AarhusINV during SCI inversion	
TOPO	m	Digital elevation model	
ALT	m	Receiver bird elevation above the TOPO	
Dist	m	Distance along profile	
RHO	Ohm m	Recovered electrical resistivity values (array of 29 channels)	
RHO_DOI	Ohm m	Recovered electrical resistivity values, masked to the depth of investigation (DOI_LOWER) (array of 29 channels)	
COND	S/m	Electrical conductivity values calculated from RHO (array of 29 channels)	
COND_DOI	S/m	Electrical conductivity values calculated from RHO, masked to the depth of investigation (DOI_LOWER) (array of 29 channels)	
ТНК	m	Thickness of layers used to discretize the subsurface (array of 28 channels)	
DEP_BOT	m	Depth to bottom of each layer (array of 28 channels)	
DEP_TOP	m	Depth to top of each layer (array of 29 channels)	
DOI_LOWER	m	Depth of investigation, calculated using a threshold = 1.2 (optimistic scenario)	
DOI_UPPER	m	Depth of investigation, calculated using a threshold = 0.6 (pessimistic scenario)	
RESDATA	N/A	Data misfit (normalized by standard deviation)	

Table A1 contains the list of channels present in *"GeoScience_BC_Nort_West_Block_2017"*. Geosoft format DBVIEW file *"INV_Final.dbview"* is also provided.



TableA1. List of channels in the final inverson database

Final maps

Table A2 contains the list of final maps delivered at phase 1 of Peace River project

Map number	Map name	Description
1.QC.001	Peace_River_North-Western_DEM	Map of Digital Elevation Model
1.QC.002	Peace_River_North-Western_DOI	Map of Depth of Investigation (DOI_LOWER)
1.QC.003	Peace_River_North- Western_GlobalMisfit	Map of inversion misfit
1.QC.004	Peace_River_North-Western_Moments	Map of SkyTEM moments used in the inversion
1.QC.005	Peace_River_North-Western_NumChan	Map of number of SkyTEM high moment channels used in the inversion
1.RHO.005	Peace_River_North- Western_RHO_dep000_005	Map of recovered electrical resistivity at depth below surface interval 0-5 m
1.RHO.010	Peace_River_North- Western_RHO_dep005_010	Map of recovered electrical resistivity at depth below surface interval 5-10 m
1.RHO.015	Peace_River_North- Western_RHO_dep010_015	Map of recovered electrical resistivity at depth below surface interval 10-15 m
1.RHO.020	Peace_River_North- Western_RHO_dep015_020	Map of recovered electrical resistivity at depth below surface interval 15-20 m
1.RHO.030	Peace_River_North- Western_RHO_dep020_030	Map of recovered electrical resistivity at depth below surface interval 20-30 m
1.RHO.040	Peace_River_North- Western_RHO_dep030_040	Map of recovered electrical resistivity at depth below surface interval 30-40 m
1.RHO.360	Peace_River_North- Western_RHO_lev350_360	Map of recovered electrical resistivity at absolute elevation interval 350-360 m
1.RHO.370	Peace_River_North- Western_RHO_lev360_370	Map of recovered electrical resistivity at absolute elevation interval 360-370 m
1.RHO.380	Peace_River_North- Western_RHO_lev370_380	Map of recovered electrical resistivity at absolute elevation interval 370-380 m
1.RHO.390	Peace_River_North- Western_RHO_lev380_390	Map of recovered electrical resistivity at absolute elevation interval 380-390 m
1.RHO.400	Peace_River_North- Western_RHO_lev390_400	Map of recovered electrical resistivity at absolute elevation interval 390-400 m
1.RHO.410	Peace_River_North- Western_RHO_lev400_410	Map of recovered electrical resistivity at absolute elevation interval 400-410 m
1.RHO.420	Peace_River_North- Western_RHO_lev410_420	Map of recovered electrical resistivity at absolute elevation interval 410-420 m
1.RHO.430	Peace_River_North- Western_RHO_lev420_430	Map of recovered electrical resistivity at absolute elevation interval 420-430 m
1.RHO.440	Peace_River_North- Western_RHO_lev430_440	Map of recovered electrical resistivity at absolute elevation interval 430-440 m
1.RHO.450	Peace_River_North- Western_RHO_lev440_450	Map of recovered electrical resistivity at absolute elevation interval 440-450 m



1.RHO.460	Peace_River_North-	Map of recovered electrical resistivity at absolute
	Western_RHO_lev450_460	elevation interval 450-460 m
1.RHO.470	Peace_River_North- Western RHO lev460 470	Map of recovered electrical resistivity at absolute elevation interval 460-470 m
	Peace River North-	Map of recovered electrical resistivity at absolute
1.RHO.480	Western_RHO_lev470_480	elevation interval 470-480 m
	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.KHU.490	Western_RHO_lev480_490	elevation interval 480-490 m
	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.KH0.500	Western_RHO_lev490_500	elevation interval 490-500 m
	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.10.510	Western_RHO_lev500_510	elevation interval 500-510 m
	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.KHU.520	Western_RHO_lev510_520	elevation interval 510-520 m
	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.КПО.550	Western_RHO_lev520_530	elevation interval 520-530 m
	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.КПО.340	Western_RHO_lev530_540	elevation interval 530-540 m
	Peace_River_North-	Map of recovered electrical resistivity at absolute
T.KHU.550	Western_RHO_lev540_550	elevation interval 540-550 m
1.RHO.560	Peace_River_North-	Map of recovered electrical resistivity at absolute
	Western_RHO_lev550_560	elevation interval 550-560 m
1 PHO 570	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.10.570	Western_RHO_lev560_570	elevation interval 560-570 m
1 RHO 580	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.1(10.500	Western_RHO_lev570_580	elevation interval 570-580 m
1 RHO 590	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.1410.070	Western_RHO_lev580_590	elevation interval 580-590 m
1 RHO 600	Peace_River_North-	Map of recovered electrical resistivity at absolute
	Western_RHO_lev590_600	elevation interval 590-600 m
1.RHO.610	Peace_River_North-	Map of recovered electrical resistivity at absolute
	Western_RHO_lev600_610	elevation interval 600-610 m
1.RHO.620	Peace_River_North-	Map of recovered electrical resistivity at absolute
	Western_RHO_lev610_620	elevation interval 610-620 m
1.RHO.630	Peace_River_North-	Map of recovered electrical resistivity at absolute
	Western_RHO_lev620_630	elevation interval 620-630 m
1.RHO.640	Peace_River_North-	Map of recovered electrical resistivity at absolute
	western_RHO_lev630_640	elevation interval 630-640 m
1.RHO.650	Peace_River_North-	Map of recovered electrical resistivity at absolute
	Western_RHO_lev640_650	elevation interval 640-650 m
1.RHO.660	Peace_River_North-	Map of recovered electrical resistivity at absolute
	western_RHO_lev650_660	elevation interval 650-660 m
1.RH0.670	Peace_River_North-	Map of recovered electrical resistivity at absolute
	western_RHO_lev660_670	elevation interval 660-670 m
1.RHO.680	Peace_River_North-	Map of recovered electrical resistivity at absolute
	Western_KHO_lev670_680	elevation interval 670-680 m
1.RHO.690	Peace_River_North-	Map of recovered electrical resistivity at absolute
	western_KHU_lev680_690	elevation interval 680-690 m
1.RHO.700	Peace_River_North-	wap of recovered electrical resistivity at absolute
	Western_KHU_lev690_/00	elevation interval 690-700 m



1.RHO.710	Peace_River_North-	Map of recovered electrical resistivity at absolute
	Deese Diver North	Man of recovered electrical resistivity at absolute
1.RHO.720	Peace_River_North-	map of recovered electrical resistivity at absolute
	Western_RHO_lev/10_/20	elevation interval 710-720 m
	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.KHU.730	Western_RHO_lev720_730	elevation interval 720-730 m
1 0110 740	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.RH0.740	Western_RHO_lev730_740	elevation interval 730-740 m
1.RHO.750	Peace_River_North-	Map of recovered electrical resistivity at absolute
	Western_RHO_lev740_750	elevation interval 740-750 m
1 0110 7/0	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.RHU.700	Western_RHO_lev750_760	elevation interval 750-760 m
1.RHO.770	Peace_River_North-	Map of recovered electrical resistivity at absolute
	Western_RHO_lev760_770	elevation interval 760-770 m
	Peace_River_North-	Map of recovered electrical resistivity at absolute
1.RHU.780	Western_RHO_lev770_780	elevation interval 770-780 m
1.RHO.790	Peace_River_North-	Map of recovered electrical resistivity at absolute
	Western_RHO_lev780_790	elevation interval 780-790 m
	Peace_River_North-	Map of recovered electrical resistivity at absolute
I.KIU.800	Western_RHO_lev790_800	elevation interval 790-800 m

Table A2. List of final maps (available in MAP and PDF formats).